

Approximate the flux variable: a simplified mixed finite element method * †

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Darcy flow model

- Single phase flows in porous media by the Darcy equation:

$$\mathbf{u} = -\frac{\mathbb{K}}{\mu} (\nabla p + \rho \mathbb{G}), \quad \Omega, \quad (1a)$$

$$\nabla \cdot \mathbf{u} = f, \quad \Omega, \quad (1b)$$

$$\boldsymbol{\nu} \cdot \mathbf{u} = g, \quad \Gamma. \quad (1c)$$

- Ω : a porous medium in \mathbb{R}^d , $d = 2, 3$, with Lipschitz boundary $\Gamma = \partial\Omega$.
- \mathbf{u} and p : the Darcy flow rate and the pressure in the fluid
- \mathbb{K} , μ , and ρ represent the permeability tensor of medium and the viscosity and the density of fluid, and \mathbb{G} denotes the gravity vector,
- $\mathbb{K} \in \mathbb{R}^{d \times d}$ is a $d \times d$ symmetric and uniformly positive definite matrix and $\mu \in L^\infty(\Omega)$ with $\mathbb{K} > \mathbb{O}$ and $\mu > 0$
- f and g denote the volumetric flow rate source or sink and the prescribed normal flux

Model continued

- Introduce the modified pressure $\tilde{p} = p + \rho g_c z$ so that

$$\mathbf{u} = -\frac{\mathbb{K}}{\mu} \nabla \tilde{p}. \quad (2)$$

- From now on, we will use \mathbf{p} in place of \tilde{p} and use \mathcal{A} in place of $\frac{\mathbb{K}}{\mu}$.
- Under the assumption that $\mathbf{f} \in \mathbf{H}^{-1}(\Omega)$ and $\mathbf{g} \in \mathbf{H}^{-\frac{1}{2}}(\Gamma)$, with the compatibility condition:

$$\langle \mathbf{f}, 1 \rangle_{\mathbf{H}^{-1}(\Omega), \mathbf{H}^1(\Omega)} = \langle \mathbf{g}, 1 \rangle_{\mathbf{H}^{-\frac{1}{2}}(\Gamma), \mathbf{H}^{1/2}(\Gamma)}, \quad (3)$$

there exists a unique solution $\mathbf{p} \in \mathbf{H}^1(\Omega)/\mathbb{R}$

- For any $\mathbf{g} \in \mathbf{H}^{-\frac{1}{2}}(\Gamma)$, set

$$\mathbf{H}_g(\text{div}; \Omega) = \{ \mathbf{v} \in \mathbf{H}(\text{div}; \Omega) \mid \boldsymbol{\nu} \cdot \mathbf{v} = \mathbf{g} \text{ on } \Gamma \}.$$

- $L_0^2(\Omega) = \{ q \in L^2(\Omega) \mid \int_{\Omega} q \, dx = 0 \}.$
- The standard mixed weak formulation: find $(\mathbf{u}, \mathbf{p}) \in \mathbf{H}_g(\text{div}; \Omega) \times L_0^2(\Omega)$

$$(\mathcal{A}^{-1} \mathbf{u}, \mathbf{v}) - (\mathbf{p}, \nabla \cdot \mathbf{v}) = 0 \quad \forall \mathbf{v} \in \mathbf{H}_0(\text{div}; \Omega), \quad (4a)$$

$$(\nabla \cdot \mathbf{u}, q) = (\mathbf{f}, q) \quad \forall q \in L_0^2(\Omega), \quad (4b)$$

Model continued+Mixed FEM

- Choose a suitable $\mathbf{u}_g \in H_g(\text{div}; \Omega)$.
- The solution $(\mathbf{u}, p) \in H_g(\text{div}; \Omega) \times L_0^2(\Omega)$ is identical to $(\mathbf{w} + \mathbf{u}_g, p)$ where $(\mathbf{w}, p) \in H_0(\text{div}; \Omega) \times L_0^2(\Omega)$ solves

$$(\mathcal{A}^{-1}\mathbf{w}, \mathbf{v}) - (p, \nabla \cdot \mathbf{v}) = -(\mathcal{A}^{-1}\mathbf{u}_g, \mathbf{v}) \quad \forall \mathbf{v} \in H_0(\text{div}; \Omega), \quad (5a)$$

$$(\nabla \cdot \mathbf{w}, q) = (f - \nabla \cdot \mathbf{u}_g, q) \quad \forall q \in L_0^2(\Omega). \quad (5b)$$

Mixed Finite Element Method: Let $V_{h,g}^{(k)} \times W_{h,0}^{(k)} \subset H_g(\text{div}; \Omega) \times L_0^2(\Omega)$ be a mixed FEM subspace. Find $(\mathbf{u}_h, p_h) \in V_{h,g}^{(k)} \times W_{h,0}^{(k)}$:

$$(\mathcal{A}^{-1}\mathbf{u}_h, \mathbf{v}_h) - (p_h, \nabla \cdot \mathbf{v}_h) = 0 \quad \forall \mathbf{v}_h \in V_{h,0}^{(k)}, \quad (6a)$$

$$(\nabla \cdot \mathbf{u}_h, q_h) = (f, q_h) \quad \forall q_h \in W_{h,0}^{(k)}. \quad (6b)$$

Mixed Finite Element Spaces $V_{h,g}^{(k)} \times W_{h,0}^{(k)}$

$$\begin{cases} \mathbb{RT}_h^{(k)} := \{v \in \mathbf{H}(\text{div}; \Omega) : v|_K \in [P_k(K)]^n \oplus \text{Span}\{\mathbf{x}\tilde{P}_k(K)\}, K \in \mathcal{T}_h\}, \\ \mathbb{BDM}_h^{(k)} := \{v \in \mathbf{H}(\text{div}; \Omega) : v|_K \in [P_k(K)]^n, K \in \mathcal{T}_h\}, \end{cases},$$

- $P_k(K)$ = the space of all polynomials up to degree k defined on K ,
 $\tilde{P}_k(K)$ = the space of all homogeneous polynomials of degree k
- $C^0(P_h^{(k)})$ the standard C^0 -conforming FE space of piecewise polynomials of degree $\leq k$ on mesh \mathcal{T}_h .
- $C^{-1}(P_h^{(k)}) = \{q \in L^2(\Omega) : q|_K \in P_k(K), K \in \mathcal{T}_h\}$,
 $C_0^{-1}(P_h^{(k)}) = C^{-1}(P_h^{(k)})/\mathbb{R} = \{q \in C^{-1}(P_h^{(k)}) \mid \int_{\Omega} q \, dx = 0\}$.
- $\mathbb{RT}_{h,g}^{(k)} = \mathbb{RT}_h^{(k)} \cap H_g(\text{div}; \Omega)$, $\mathbb{BDM}_{h,g}^{(k)} = \mathbb{BDM}_h^{(k)} \cap H_g(\text{div}; \Omega)$,
- The family of RTN/BDM-BDDF Mixed FEM spaces of index k

$$M_{h,g}^{(k)} := V_{h,g}^{(k)} \times W_{h,0}^{(k)} := \begin{cases} \mathbb{RT}_{h,g}^{\iota(k)} \times C_0^{-1}(P_h^{(k)}), \\ \mathbb{BDM}_{h,g}^{\iota(k)} \times C_0^{-1}(P_h^{(k)}), \end{cases}$$

$$\iota(k) = \begin{cases} k, & \text{if } V_h^{(k)} = \mathbb{RT}_h^{\iota(k)}, \\ k+1, & \text{if } V_h^{(k)} = \mathbb{BDM}_h^{\iota(k)}. \end{cases}$$

Two-step Hybrid Finite Element Method

(with JaEun Ku and Young Ju Lee (ESAIM: Mathematical Modelling and Numerical Analysis 51 (4), 1303-1316, 2017) for homogeneous Dirichlet boundary condition)

Mixed Finite Element Method: Find $(\mathbf{u}_h, p_h) \in V_{h,g}^{(k)} \times W_{h,0}^{(k)}$:

$$(\mathcal{A}^{-1}\mathbf{u}_h, \mathbf{v}_h) - (p_h, \nabla \cdot \mathbf{v}_h) = 0 \quad \forall \mathbf{v}_h \in V_{h,0}^{(k)}, \quad (7a)$$

$$(\nabla \cdot \mathbf{u}_h, q_h) = (f, q_h) \quad \forall q_h \in W_{h,0}^{(k)}. \quad (7b)$$

Step 1 (Coarse-grid solution) On a coarse mesh \mathcal{T}_H , obtain the standard Galerkin solution p_H^G satisfying

$$(\mathcal{A} \nabla p_H^G, \nabla q_H) = (f, q_H) \quad \forall q_H \in C_0^0(P_H^{(k)}). \quad (8)$$

Step 2 (Fine-grid solution) On a finer mesh \mathcal{T}_h , find $\mathbf{u}_h \in V_{h,g}^{(k)}$ such that

$$(\nabla \cdot \mathbf{u}_h, \nabla \cdot \mathbf{v}_h) + \delta(\mathcal{A}^{-1}\mathbf{u}_h, \mathbf{v}_h) = (f, \nabla \cdot \mathbf{v}_h) + \delta(p_H^G, \nabla \cdot \mathbf{v}_h) \quad \forall \mathbf{v}_h \in V_{h,0}^{(k)}. \quad (9)$$

Advantages of New Hybrid Method

- Well-developed fast solvers on fine grid (Arnold–Falk–Winther (1997,2000), $H(\text{div})$ multigrid preconditioner for $\Lambda(u, v) = \rho^2(u, v) + \kappa^2(\nabla \cdot u, \nabla \cdot v)$; Hiptmair–Xu (2007, Nodal auxillary subspace precond. ...))
- Of substantially smaller problem size.
- Elimination of the need for artificial stabilization techniques (no *inf-suf* condition.)

$$\inf_{q_h \in W_h^{(k)}} \sup_{v_h \in V_h^{(k)}} \frac{(\nabla \cdot v_h, q_h)}{\|v_h\|_{H^1(\Omega)} \|q_h\|_{L^2(\Omega)}} = \beta > 0. \quad (10)$$

- A practical and sharp *a posteriori* error estimator
- Play with the parameter δ .

Comparison with the Mixed FE solution

Mixed FEM $(u_h^M, p_h^M) \in V_{h,g}^{(k)} \times W_{h,0}^{(k)}$

$$\begin{aligned} (\mathcal{A}^{-1} u_h^M, v_h) - (\nabla \cdot v_h, p_h^M) &= 0 \quad \forall v_h \in V_{h,0}, \\ (\nabla \cdot u_h^M, q_h) &= (f, q_h) \end{aligned}$$

$$\begin{aligned} \delta(\mathcal{A}^{-1} u_h^M, v_h) - \delta(\nabla \cdot v_h, p_h^M) &= 0, \\ (\nabla \cdot u_h^M, q_h) &= (f, q_h) \end{aligned}$$

Taking $q_h = \nabla \cdot v_h$,

$$(\nabla \cdot u_h^M, \nabla \cdot v_h) + \delta(\mathcal{A}^{-1} u_h^M, v_h) = (f + \delta p_h^M, \nabla \cdot v_h).$$

Two-step Hybrid Method $(u_h, p_H^G) \in V_{h,g}^{(k)} \tilde{\times} C_0^0(P_H^{(k)})$

$$(\nabla \cdot u_h, \nabla \cdot v_h) + \delta(\mathcal{A}^{-1} u_h, v_h) = (f + \delta p_H^G, \nabla \cdot v_h) \quad \forall v_h \in V_{h,0}.$$

Difference between the Two-step Hybrid Method and the MFEM

$$(\nabla \cdot (u_h^M - u_h), \nabla \cdot v_h) + \delta(\mathcal{A}^{-1} (u_h^M - u_h), v_h) = \delta(p_h^M - p_H^G, \nabla \cdot v_h).$$

Basic Error Estimates with H^2 regularity

Theorem (In case of full regularity, i.e., if $u \in H^2$,)

$$\begin{aligned}\|u - u_h\|_{L_2(\Omega)} &\leq C \|u - \Pi_h u\|_{L_2(\Omega)} \\ &\quad + \sqrt{\delta} h \|u - \Pi_h u\|_{H(\text{div})} + C \sqrt{\delta} H \|p - p_h^G\|_{W_2^1(\Omega)} \\ &\leq Ch \|u\|_1 + Ch^2 \|\nabla \cdot u\|_1 + C \sqrt{\delta} H^2 \|p\|_2.\end{aligned}$$

If $\iota(k) = 0$, then the *optimal choice* is

$$h = \sqrt{\delta} H^2.$$

New Simple approximation scheme

(submitted with Imbumn Kim, JaEun Ku, and Young Ju Lee)

Scheme (Simple single-step scheme)

Find $u_h \in V_{h,g}^{(k)}$ such that

$$(\nabla \cdot u_h, \nabla \cdot v_h) + \delta(\mathcal{A}^{-1}u_h, v_h) = (f, \nabla \cdot v_h) \quad \forall v_h \in V_{h,0}^{(k)}. \quad (11)$$

- Free from the Mixed FE pair of discrete LBB condition.
- Even do not solve for coarse mesh pressure approximation p_H^G
- Not need any discrete function space for pressure if we want to approximate only flux.

Proposition (Quasi-orthogonality property)

$$(\nabla \cdot (u - u_h), \nabla \cdot v_h) + \delta(\mathcal{A}^{-1}(u - u_h), v_h) = \delta(p, \nabla \cdot v_h), \quad v_h \in V_{h,0}^{(k)}, \quad (12)$$

Error analysis for the flux

Theorem

Assume that the solution $(\mathbf{u}, p) \in H_g(\text{div}; \Omega) \times L_0^2(\Omega)$ to (4) belongs to $H^{r-1+\alpha}(\Omega) \times H^{r+\alpha}(\Omega)$ for some $r \geq 1$ and $\alpha \in [0, 1]$. For $\iota(k) + 1 \leq r$, let $\mathbf{u}_h \in V_{h,g}^{(k)}$ be the solution satisfying (11). Then,

$$\|\mathbf{u} - \mathbf{u}_h\| \leq C(h^s + \sqrt{\delta}) \|\mathbf{u}\|_s, \quad (13)$$

for $0 \leq s \leq \min(r + \alpha - 1, \iota(k) + 1)$. Furthermore, if $\nabla \cdot \mathbf{u} \in H^{r-1+\alpha}(\Omega)$ in addition, we have

$$\|\nabla \cdot (\mathbf{u} - \mathbf{u}_h)\| \leq C(h^s + \delta) \left(\|\nabla \cdot \mathbf{u}\|_s + \|\mathbf{u}\|_s \right). \quad (14)$$

for $0 \leq s \leq \min(r + \alpha - 1, k + 1)$.

Numerical Example

- $\Omega = (0, 100) \times (0, 20)$
- $p = 1000$ for $x = 0$ (Left bdry); $p = 10$ for $x = 100$ (Right bdry); $\nu \cdot u = 0$ for $y = 0$ or $y = 20$ (Top & Bottom bdry)
- $h = 0.5$; $\delta = 2.5 \times 10^{-5}$
- The numerical results agree well with those by the standard MFEM approximation.
- Heterogeneous permeability tensor:

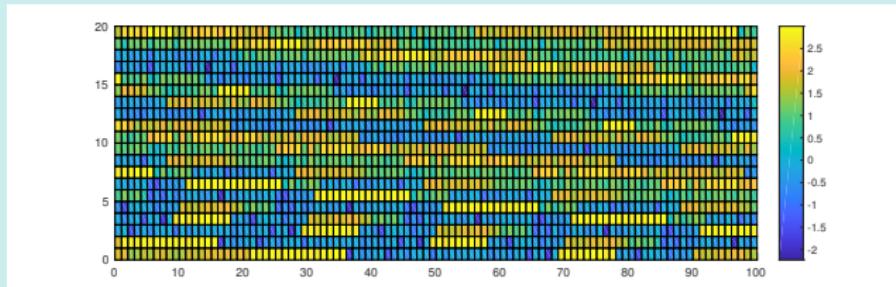


Figure: Permeability tensor with log scale from SPE10 model 1

Numerical Example

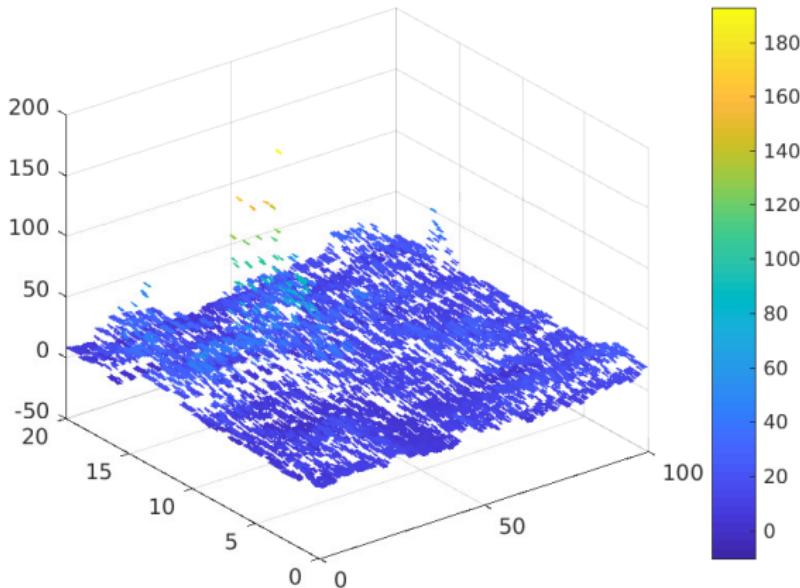


Figure: The x-component of velocity fields by Simple single-step scheme on $\mathbb{RT}_{g,h}^{(0)}$.

Numerical Example

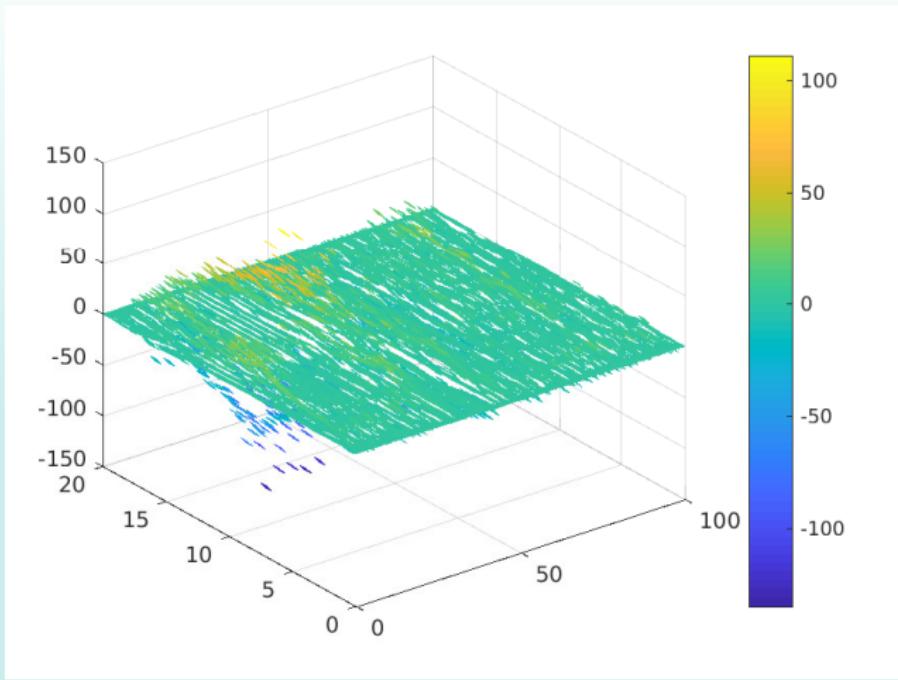


Figure: The y-component of velocity fields by Simple single-step scheme on $\mathbb{RT}_{g,h}^{(0)}$.

Numerical Example

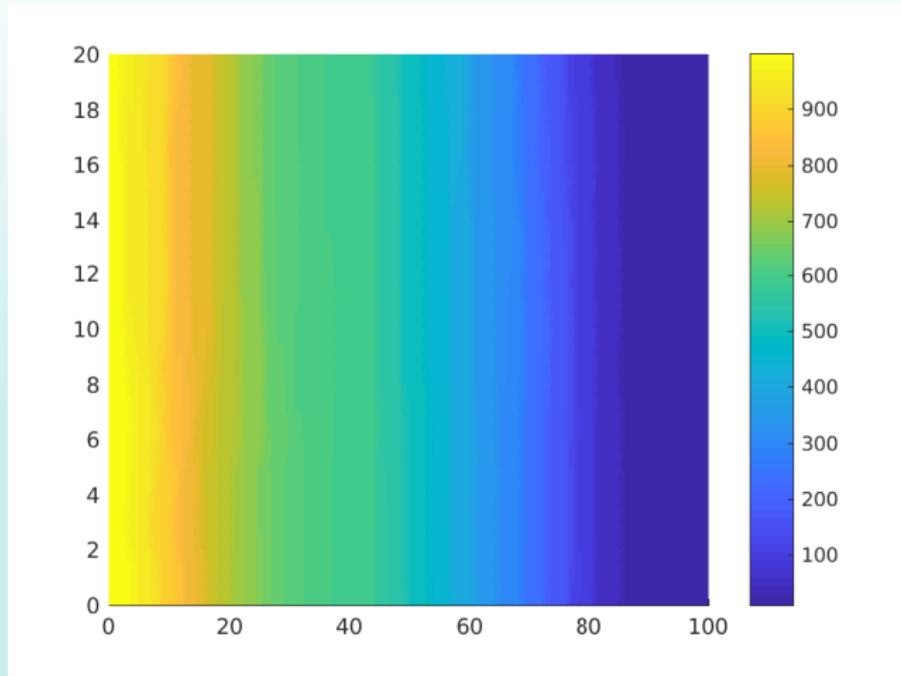


Figure: The pressure p obtained by Simple single-step scheme on $\mathbb{RT}_{g,h}^{(0)}$ and then on $C^{-1}(P_h^{(0)})$.

Numerical Example

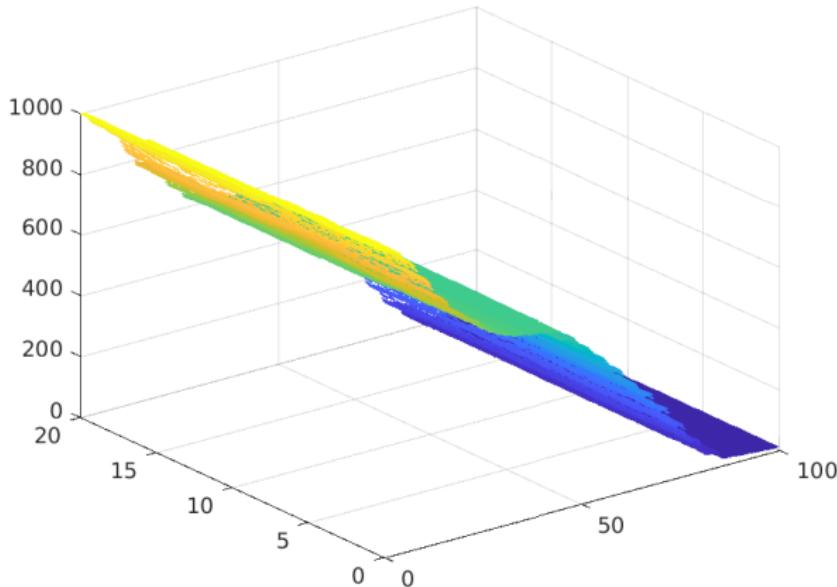


Figure: The pressure p from another direction by Simple single-step scheme on $\mathbb{RT}_{g,h}^{(0)}$.

Iterative Improvement Approximation to u_h

(In preparation with JaEun Ku)

Scheme (Iterative Improvement: Generation of $(u_h^{(n)})_{n=0}^{\infty} \subset V_{h,g}^{(k)}$)

1. Choose $u_h^{(0)} \in V_{h,g}^{(k)}$ such that $P_h(\mathcal{A}^{-1}u_h^{(0)}) \in \nabla_h W_{h,\Gamma_\nu}^{(k)}$;
2. For $n = 1, 2, \dots$, calculate $u_h^{(n)} \in V_{h,g}^{(k)}$ fulfilling

$$(\nabla \cdot u_h^{(n)}, \nabla \cdot v_h) + \delta(\mathcal{A}^{-1}u_h^{(n)}, v_h) = (f, \nabla \cdot v_h) + \delta(\mathcal{A}^{-1}u_h^{(n-1)}, v_h) \quad \forall v_h \in V_{h,0}^{(k)}. \quad (15)$$

Remark (Practical choice of initial approximation)

Choose $u_h^{(0)} \in V_{h,g}^{(k)}$ such that $P_h(\mathcal{A}^{-1}u_h^{(0)}) \in V_{h,g}^{(k)}$ is recommended as follows:
find $w_h \in V_{h,g}^{(k)}$ fulfilling

$$(w_h, v_h) = -(f, \nabla \cdot v_h) \quad \forall v_h \in V_{h,0}^{(k)}.$$

Indeed, $w_h = \nabla_h P_h f$. Then, choose $u_h^{(0)} = \mathcal{A}w_h$.

Approximation property

The following estimate shows that the new approximation $u_h^{(n)}$ is a better approximation than the original $u_h^{(0)}$.

Proposition

Let $u_h^{(0)} \in V_{h,g}^{(k)}$ be an approximation to u of Step 1, and let $(u_h^M, p_h^M) \in M_h^{(k)}$ be the mixed finite element solution satisfying (7). Let $u_h^{(n)} \in V_{h,g}^{(k)}$ be the solution satisfying (15). Then, for $n \geq 1$, we have

$$\|\mathcal{A}^{-1/2}(u_h^{(n)} - u_h^M)\|^2 + \frac{2}{\delta} \|\nabla \cdot (u_h^{(n)} - u_h^M)\| \leq \|\mathcal{A}^{-1/2}(u_h^{(n-1)} - u_h^M)\|^2 \quad (16)$$

Theorem (Convergence without rate)

$$\lim_{n \rightarrow \infty} \|u_h^{(n)} - u_h^M\|^2 = 0.$$

Numerical examples

- Let $\Omega = (0, 1)^2$ and consider

$$\mathbf{u} + \nabla p = \mathbf{0}, \quad \Omega, \quad (17a)$$

$$\nabla \cdot \mathbf{u} = f, \quad \Omega, \quad (17b)$$

$$p = 0, \quad \partial\Omega. \quad (17c)$$

- f : generated by the analytic solution $p(x, y) = (x - x^2)(y - y^2)$.
- Uniform triangulations of Ω are adopted in our numerical simulation;
- $\mathbb{RT}_{h,\Gamma_\nu}^{(0)}$ space is employed;
- Initial guess $\mathbf{u}_h^{(0)} = \vec{0}$
- $\|\mathbf{u}_h^{(n)} - \mathbf{u}_h^{(n-1)}\| < 10^{-10}$.

Numerical results $\delta = \frac{1}{2^6}$

$\delta=1; h = \frac{1}{2^6}$	n = 1	n = 2	n = 3	n = 4	n = 5
$\ u - u_h^{(n)}\ $	7.49E-3	2.35E-3	2.33E-3	2.33E-3	2.33E-3
$\ u_h^{(n)} - u_h^{(n-1)}\ $	2.02E-2	4.61E-5	1.09E-7	2.49E-10	5.79E-13

$\delta=0.1; h = \frac{1}{2^6}$	n = 1	n = 2	n = 3	n = 4	n = 5
$\ u - u_h^{(n)}\ $	2.44E-3	2.33E-3	2.33E-3	-	-
$\ u_h^{(n)} - u_h^{(n-1)}\ $	2.02E-2	5.50E-7	1.40E-11	-	-

$\delta=1; h = \frac{1}{2^7}$	n = 1	n = 2	n = 3	n = 4	n = 5
$\ u - u_h^{(n)}\ $	7.22E-3	1.21E-3	1.16E-3	1.16E-3	1.16E-3
$\ u_h^{(n)} - u_h^{(n-1)}\ $	2.02E-2	4.61E-5	1.07E-7	2.49E-10	5.79E-13

$\delta=0.1; h = \frac{1}{2^7}$	n = 1	n = 2	n = 3	n = 4	n = 5
$\ u - u_h^{(n)}\ $	1.38E-3	1.16E-3	1.16E-3	-	-
$\ u_h^{(n)} - u_h^{(n-1)}\ $	2.02E-2	5.50E-7	1.40E-11	-	-

Thank you for your attention !!!