

# New Homogenization Method for Diffusion Problems: Numerical Results

Kramarenko Vasily <sup>1</sup>   Yuri Kuznetsov <sup>2</sup>

<sup>1</sup>Institute of Numerical Mathematics, Moscow

<sup>2</sup>University of Houston

August, 2018

- Classical problem formulation
- Saddle point formulation
- Asymptotic expansions
- Convergence estimate
- Numerical results 1
- Numerical results 2

Let  $\Omega$  be a polygon and  $\omega_s$  be non-overlapping polygonal sub-domains in  $\Omega$ , such that  $\partial\omega_s \cap \partial\omega_t = \emptyset$  and  $\partial\omega_s \cap \partial\Omega = \emptyset$ ,  $s, t = \overline{1, m}$ .

We consider the diffusion problem

$$\begin{aligned} -\nabla [K(x)\nabla u] &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega \end{aligned} \quad (1)$$

with the diffusion coefficient

$$K(x) = \begin{cases} 1 + \frac{1}{\varepsilon_s} & \text{in } \omega_s, s = \overline{1, m}, \\ 1 & \text{in } \Omega \setminus \overline{\omega}_s, \end{cases} \quad (2)$$

where  $\varepsilon_s \equiv \text{const} > 0$  in  $\omega_s$ ,  $s = \overline{1, m}$ .

We shall call  $\{\omega_s\}$  inclusions.

In the variational form: find  $u \in H_0^1(\Omega)$  such that

$$\int_{\Omega} (K(x)\nabla u) \cdot \nabla v \, dx \equiv \int_{\Omega} \nabla u \cdot \nabla v \, dx + \sum_{s=1}^m \frac{1}{\varepsilon_s} \int_{\omega_s} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f v \, dx \quad (3)$$

$$\forall v \in H_0^1(\Omega)$$

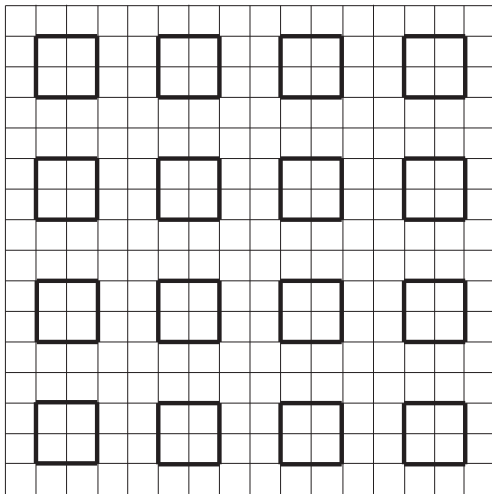
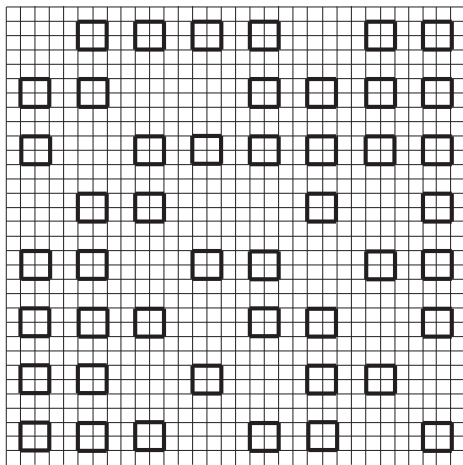


Figure: Periodic distribution of  $\omega_s$ ,  $s = \overline{1, m}$  with  $d = \frac{1}{8}$ ,  $h = \frac{1}{16}$ ,  $m = 16$ .

# Example of $\Omega$



**Figure:** Random distribution of  $\omega_s$ ,  $s = \overline{1, m}$  with  $d = \frac{1}{16}$ ,  $h = \frac{1}{32}$ ,  $m = 46$ .

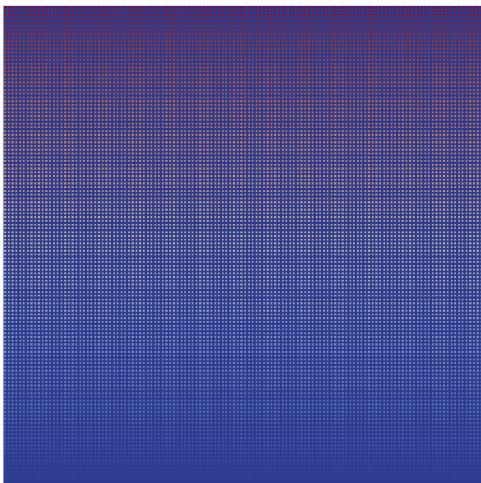


Figure: Large number of inclusions.

Let  $\Omega_h$  be a triangular mesh in  $\Omega$  conforming with  $\partial\Omega$  and  $\partial\omega_s$ ,  $s = \overline{1, m}$ , and  $V_h$  be the P1 finite element subspace of  $H_0^1(\Omega)$ . Then the finite element discretization to (3) reads as follows: find  $u_{\varepsilon, h} \in V_h$ , such that

$$\int_{\Omega} \nabla u_{\varepsilon, h} \cdot \nabla v_h \, dx + \sum_{s=1}^m \frac{1}{\varepsilon_s} \int_{\omega_s} \nabla u_{\varepsilon, h} \cdot \nabla_h \, dx = \int_{\Omega} f v_h \, dx \quad (4)$$

The above P1 FEM results in the algebraic system

$$A_{\varepsilon} \bar{u}_{\varepsilon} \equiv A \bar{u}_{\varepsilon} + \begin{bmatrix} \Sigma_s^{-1} B_{\omega} & 0 \\ 0 & 0 \end{bmatrix} \bar{u}_{\varepsilon} = \bar{f} \quad (5)$$



with the matrix  $A \sim -\Delta_h$ :

$$(A\bar{u}, \bar{v}) = \int_{\Omega} \nabla u_h \cdot \nabla v_h \, dx \quad \forall u_h, v_h \in V_h, \quad (6)$$

with the block diagonal matrix

$$B_{\omega} = \text{diag} \left\{ B_{\omega,1}, \dots, B_{\omega,m} \right\} \quad (7)$$

where

$$(B_{\omega,s}, \bar{u}_s, \bar{v}_s) = \int_{\omega_s} \nabla u_{s,h} \cdot \nabla v_{s,h} \, dx \quad \forall u_{s,h}, v_{s,h} \in V_{s,h}, \quad s = \overline{1, m}, \quad (8)$$

and with the block diagonal matrix

$$\Sigma_s = \text{diag} \left\{ \varepsilon_1 I_1, \dots, \varepsilon_m I_m \right\} \quad (9)$$

where  $I_s$  are the underlying identity matrices,  $s = \overline{1, m}$ . Here,  $V_{s,h}$  is the restriction of  $V_h$  onto  $\bar{\omega}_s$ ,  $s = \overline{1, m}$ .

Define sub-vectors

$$\bar{p}_{\varepsilon,s} = \frac{1}{\varepsilon} \bar{u}_{\varepsilon,s} \quad (10)$$

$s = \overline{1, m}$ . We replace the original algebraic system (5) with the s.p.d. matrix  $A_\varepsilon$  by the equivalent saddle-point system

$$\begin{aligned} A\bar{u}_\varepsilon + B^T\bar{p}_\varepsilon &= \bar{f} \\ B\bar{u}_\varepsilon - \Sigma_\varepsilon B_\omega \bar{p}_\varepsilon &= 0 \end{aligned} \quad (11)$$

where

$$B = [B_\omega \quad 0] \quad (12)$$

and

$$\bar{p}_\varepsilon^T = [\bar{p}_{\varepsilon,1}^T, \dots, \bar{p}_{\varepsilon,m}^T] \quad (13)$$

## Another definition of saddle-point system

Replace the original FE problem by the problem: find  $u_{\varepsilon,h} \in V_h$ ,  $p_{\varepsilon,s,h} \in V_{s,h}$ ,  $s = \overline{1,m}$  such that

$$\int_{\Omega_h} (\nabla u_{\varepsilon,h}) \cdot \nabla v_h \, dx + \sum_{s=1}^m \int_{\omega_s} (\nabla p_{\varepsilon,s,h}) \cdot \nabla v_h \, dx = \int_{\Omega} f v_h \, dx \quad (14)$$

$$\int_{\omega_s} (\nabla u_{\varepsilon,s}) \cdot q_{s,h} \, dx - \varepsilon_s \int_{\omega_s} (\nabla p_{\varepsilon,s,h}) \cdot \nabla q_{s,h} \, dx = 0 \quad (15)$$

$\forall v_h \in V_h$ ,  $q_{s,h} \in V_{s,h}$ ,  $s = \overline{1,m}$ . This FE problem results in the same saddle-point algebraic system (11).

Here

$$p_{\varepsilon,s,h} = \frac{1}{\varepsilon_s} u_{\varepsilon,s} \text{ in } \overline{\omega}_s, \quad s = \overline{1,m} \quad (16)$$

The above replacement of system (5) by system (11) as well as the preconditioned iterative solution methods for system (11) were proposed in [Kuznetsov 2000] for the case of one inclusion and in [Kuznetsov 2009] for the case of multiple inclusions.

Yu. Kuznetsov, "New Iterative Methods for Singular Perturbed Positive Definite Matrices", *Russian Journal of Numerical Analysis and Mathematical Modeling*, **15:1**, 2000, pp. 65–71.

Yu. Kuznetsov, "Preconditioned iterative methods for algebraic saddle-point problems", *Russian Journal of Numerical Mathematics*, **17:1**, 2009, pp. 67–75.

Assume that  $\varepsilon_s = \varepsilon$ ,  $s = \overline{1, m}$ . For approximation of the solution of the system

$$\mathcal{A}_\varepsilon \begin{bmatrix} \bar{u}_\varepsilon \\ \bar{p}_\varepsilon \end{bmatrix} \equiv \begin{bmatrix} A & B^T \\ B & -\Sigma B_\omega \end{bmatrix} \begin{bmatrix} \bar{u}_\varepsilon \\ \bar{p}_\varepsilon \end{bmatrix} = \begin{bmatrix} \bar{f} \\ 0 \end{bmatrix} \quad (17)$$

we apply the “homogenization” method based on the expansions

$$\bar{u}_\varepsilon^{(r)} = \sum_{l=0}^r \varepsilon^l \bar{u}^{(l)}, \quad (18)$$

$$\bar{p}_\varepsilon^{(r)} = \sum_{l=0}^r \varepsilon^l \bar{p}^{(l)}, \quad (19)$$

where the vectors  $\bar{u}^{(l)}, \bar{p}^{(l)}, l = \overline{0, r}$  satisfy the systems

$$\mathcal{A}_0 \begin{bmatrix} \bar{u}^{(0)} \\ \bar{p}^{(0)} \end{bmatrix} \equiv \begin{bmatrix} A & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} \bar{u}^{(0)} \\ \bar{p}^{(0)} \end{bmatrix} = \begin{bmatrix} \bar{f} \\ 0 \end{bmatrix} \quad (20)$$

and

$$\mathcal{A}_0 \begin{bmatrix} \bar{u}^{(l)} \\ \bar{p}^{(l)} \end{bmatrix} = \begin{bmatrix} 0 \\ B_\omega \bar{p}^{(l-1)} \end{bmatrix} \quad (21)$$

*Remark:* Without loss of generality we may assume that the solution vectors  $\bar{p}_\varepsilon$  in (19) and  $\bar{p}^{(l)}$  in (20), (21) are orthogonal to  $\ker B_\omega$ . We recall that  $\ker B_{\omega, s}$  consists of the vectors with constant components,  $s = \overline{1, m}$ . To this end  $\dim \ker B_\omega = m$ .

The error estimate

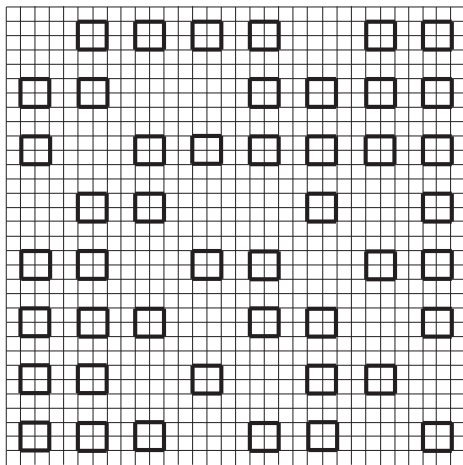
$$\|\bar{u}_\varepsilon - \bar{u}_\varepsilon^{(r)}\|_A \leq \|\bar{p}_\varepsilon - \bar{p}_\varepsilon^{(r)}\|_{B_\omega} \leq \frac{\varepsilon^r}{\mu_{h,*}^{r+1}} \|f\|_{A^{-1}} \quad (22)$$

can be derived [Kuznetsov 2018]. It was proved that in the case of regular shaped quasiuniform meshes  $\Omega_h$  the value of  $\mu_{h,*}$  is bounded from below by a positive constant independent of  $\Omega_h$ . where  $\mu_{h,*}$  is the minimal nonzero eigenvalue of the eigenvalue problem

$$BA^{-1}B^T\bar{w} = \mu B_\omega\bar{w} \quad (23)$$

Yu. Kuznetsov, "New homogenization method for diffusion equations", *Russian Journal of Numerical Mathematics*, **33:2**, 2018, pp. 85–93.

# Model Problem 1: numerical results



**Figure:** Random distribution of  $\omega_s$ ,  $s = \overline{1, m}$  with  $d = \frac{1}{16}$ ,  $h = \frac{1}{32}$ ,  $m = 46$ .



# Model Problem 1: numerical results

Let  $\Omega = (0 : 1) \times (0 : 1)$  be the unite square with square  $d \times d$  inclusions  $\omega_s$ ,  $s = \overline{1, m}$ , and  $\Omega_h$  be a square mesh with the mesh step size  $h = \frac{d}{2^t}$ ,  $t = 1, 2, \dots$ . In numerical test we compute the values

$$\delta \bar{u}^{(l)} = \frac{\|\bar{u}_\varepsilon - \bar{u}^{(r)}\|_A}{\|f\|_{A^{-1}}} \quad \delta \bar{p}^{(l)} = \frac{\|\bar{p}_\varepsilon - \bar{p}^{(r)}\|_{B_\omega}}{\|f\|_{A^{-1}}}, \quad r = 0, 1, 2, \dots \quad (24)$$

Here,

$$\|\bar{\psi}_A\| = (A\bar{\psi}, \bar{\psi})^{\frac{1}{2}} \quad \|\bar{q}\|_{B_\omega} = (B_\omega \bar{q}, \bar{q})^{\frac{1}{2}} \quad (25)$$

To compute the vectors  $\bar{u}_\varepsilon$ ,  $\bar{p}_\varepsilon$ ,  $\bar{u}^{(r)}$ ,  $\bar{p}^{(r)}$ ,  $r = 0, 1, 2, \dots$  we use the PCG Uzawa with the preconditioner  $B_\omega^+$ , i.e. we solve the systems

$$(\Sigma_\varepsilon B_\omega + BA^{-1}B^T) \bar{p} = \bar{g}, \quad g \in \text{im} B_\omega \quad (26)$$

by the classical PCG method.

In periodic distribution of  $\{\omega_s\}$  the distances between neighboring  $\omega_s$  and  $\omega_t$ ,  $s \neq t$  are equal to  $d$ , whereas distance between  $\omega_s$  and  $\Omega$  is equal to  $d/2$ ,  $s, t = \overline{1, m}$ . Random distribution of  $\{\omega_s\}$  is a subset of the periodic distribution. We solve the systems with the matrices  $A$  in the Uzawa algorithm by the PCG method with the AMG preconditioner. It takes about 12-14 AMG-PCG iterations to solve a system with relative accuracy  $10^{-8}$

*Remark:* To implement the preconditioner  $B_\omega^+$  - generalized inverse of  $B_\omega$  we use the fact that

$$B_\omega^+ B = B_\omega^+ [B_\omega \quad 0] = [I - Q \quad 0] \quad (27)$$

where  $Q$  is the  $M$ -orthogonal projector onto  $\ker B_\omega$  where  $M$  is the underlying mass matrix.

# Example of inclusion distribution

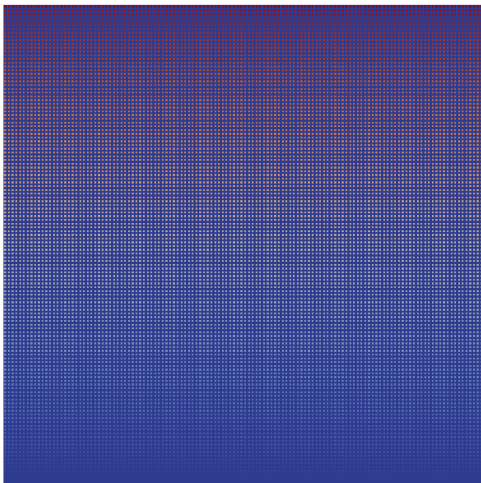


Figure: 16384 inclusions.

# Model Problem 1: numerical results

| $\varepsilon$    | $10^{-1}$ | $10^{-2}$ | $10^{-3}$ | $10^{-4}$ |
|------------------|-----------|-----------|-----------|-----------|
| $\delta u^{(0)}$ | 9.3e-2    | 8.0e-3    | 1.0e-3    | 1.0e-4    |
| $\delta p^{(0)}$ | 1.6e-1    | 1.9e-2    | 2.0e-3    | 2.0e-4    |
| $\delta u^{(1)}$ | 2.3e-2    | 2.6e-4    | 2.9e-6    | 2.9e-8    |
| $\delta p^{(1)}$ | 4.0e-2    | 5.4e-4    | 5.0e-5    | 5.0e-8    |
| $\delta u^{(2)}$ | 6.6e-3    | 9.5e-6    | 8.3e-9    | 8.4e-12   |
| $\delta p^{(2)}$ | 1.0e-2    | 1.6e-5    | 1.3e-8    | 1.2e-11   |
| $\delta u^{(3)}$ | 1.8e-3    | 3.0e-7    | 2.3e-11   | 6.5e-13   |
| $\delta p^{(3)}$ | 2.6e-3    | 5.3e-7    | 3.4e-11   | 8.5e-13   |

Table:  $d = \frac{1}{256}$ ,  $h = \frac{1}{512}$ ,  $m = 16384$

# Model Problem 1: numerical results

| $\varepsilon$    | $10^{-1}$ | $10^{-2}$ | $10^{-3}$ | $10^{-4}$ |
|------------------|-----------|-----------|-----------|-----------|
| $\delta u^{(0)}$ | 7.3e-2    | 9.6e-3    | 9.0e-4    | 9,8e-5    |
| $\delta p^{(0)}$ | 1.6e-1    | 2.0e-2    | 2.0e-3    | 2.0e-4    |
| $\delta u^{(1)}$ | 2.2e-2    | 2.9e-4    | 3.0e-6    | 3.0e-8    |
| $\delta p^{(1)}$ | 4.4e-2    | 5.4e-4    | 5.5e-6    | 5.5e-8    |
| $\delta u^{(2)}$ | 7.0e-3    | 9.1e-6    | 9.4e-9    | 9,2e-12   |
| $\delta p^{(2)}$ | 1.2e-2    | 1.5e-5    | 1.6e-8    | 1.5e-11   |
| $\delta u^{(3)}$ | 2.2e-3    | 2.8e-7    | 3.1e-11   | 5.9e-13   |
| $\delta p^{(3)}$ | 3.7e-3    | 4.6e-7    | 5.0e-11   | 6.4e-13   |

Table:  $d = \frac{1}{128}$ ,  $h = \frac{1}{512}$ , 4096

# Model Problem 1: numerical results

| $\varepsilon$    | $10^{-1}$ | $10^{-2}$ | $10^{-3}$ | $10^{-4}$ |
|------------------|-----------|-----------|-----------|-----------|
| $\delta u^{(0)}$ | 6.3e-2    | 8.0e-3    | 8.0e-4    | 8.3e-5    |
| $\delta p^{(0)}$ | 1.6e-1    | 1.9e-2    | 2.0e-3    | 2.0e-4    |
| $\delta u^{(1)}$ | 2.0e-3    | 2.6e-4    | 2.7e-6    | 2.7e-8    |
| $\delta p^{(1)}$ | 4.3e-2    | 5.4e-4    | 5.6e-6    | 5.6e-8    |
| $\delta u^{(2)}$ | 6.9e-3    | 9.0e-6    | 9.2e-9    | 4.1e-11   |
| $\delta p^{(2)}$ | 1.3e-4    | 1.6e-5    | 1.7e-8    | 5.0e-11   |
| $\delta u^{(3)}$ | 2.3e-3    | 3.0e-7    | 4.4e-11   | 4.0e-11   |
| $\delta p^{(3)}$ | 4.1e-3    | 5.3e-7    | 7.5e-11   | 4.8e-11   |

Table:  $d = \frac{1}{64}$ ,  $h = \frac{1}{512}$ ,  $m = 1024$

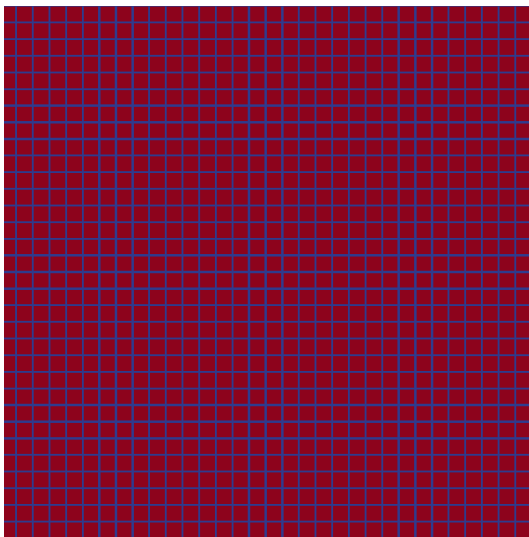


Figure: Regular distribution of  $\omega_s$ ,  $s = \overline{1, m}$  with ratio 1:7.

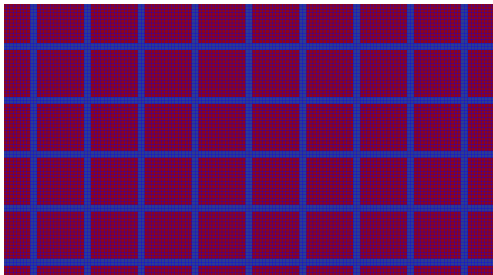


Figure: Regular distribution of  $\omega_s$ ,  $s = \overline{1, m}$  with ratio 1:7.

In this set of numerical experiments we investigate dependence of  $\mu_{h,*}$  of the ratio  $d_{st} : d_s$ .

We also investigate the accuracy of the approximate solutions of the value

$$q_{\varepsilon, h} = \frac{\varepsilon}{\mu_{h,*}}. \quad (28)$$



| ratio $d_s : d_{st}$ | $\mu_{h,*}$ | Number of Uzawa-PCG iterations |
|----------------------|-------------|--------------------------------|
| 1:1 (m=16384)        | 0.216       | 11                             |
| 1:3 (m=4096)         | 0.135       | 14                             |
| 1:7 (m=1024)         | 0.077       | 17                             |
| 1:15 (m=256)         | 0.042       | 21                             |
| 1:31 (m=64)          | 0.021       | 23                             |
| 1:63 (m=8)           | 0.011       | 25                             |

Table:  $h = \frac{1}{512}$  periodic distribution.

In this series of numerical experiments we consider the situation when distances  $d_{s,t}$  between periodically distributed inclusions are much smaller than the series  $d_s$  of the inclusions. We compute the underlying values of  $\mu_{h,*}$  and compare the theoretical estimates [Kuznetsov 2018]

$$\frac{\|\bar{u}_\varepsilon - \bar{u}^{(r)}\|_A}{\|f\|_{A^{-1}}} \leq \delta \bar{p}^{(l)} = \frac{\|\bar{p}_\varepsilon - \bar{p}^{(r)}\|_{B_\omega}}{\|f\|_{A^{-1}}} \leq \frac{\varepsilon^r}{\mu_{h,*}^{r+1}} \quad (29)$$

with numerically obtained results. We also give the numbers of Uzawa PCG iterations needed to solve the underlying saddle point algebraic systems with the relative accuracy  $10^{-6}$ .

# Model problem 2: numerical results

| ratio   | 1:1    | 1:3    | 1:7    | 1:15   | 1:31   |
|---|--------|--------|--------|--------|--------|
| $q_{\varepsilon,h} = \frac{\varepsilon}{\mu_{h,*}}$ | 0.462  | 0.740  | 1.29   | 2.38   | 4.76   |
| $\delta u^{(0)}$                                    | 8.7e-2 | 5.6e-2 | 4.0e-2 | 3.3e-2 | 3.8e-2 |
| $\delta p^{(0)}$                                    | 1.6e-1 | 1.3e-1 | 1.1e-1 | 1.0e-1 | 1.3e-1 |
| $\delta p^{(1)}$                                    | 2.3e-2 | 1.6e-2 | 1.4e-2 | 3.2e-2 | 1.0e-1 |
| $\delta u^{(1)}$                                    | 4.0e-2 | 3.0e-2 | 2.9e-2 | 7.3e-2 | 3.3e-1 |
| $\delta u^{(2)}$                                    | 6.5e-3 | 5.7e-3 | 9.3e-3 | 5.4e-2 | 3.6e-1 |
| $\delta p^{(2)}$                                    | 1.0e-2 | 9.4e-3 | 1.7e-2 | 1.2e-1 | 1.15   |
| $\delta u^{(3)}$                                    | 1.8e-3 | 2.0e-3 | 7.7e-3 | 9.6e-2 | 1.27   |
| $\delta p^{(3)}$                                    | 2.6e-3 | 3.2e-3 | 1.5e-2 | 2.3e-1 | 4.06   |

Table:  $\varepsilon = 10^{-1}, h = \frac{1}{512}$

# Model problem 2: numerical results

| ratio   | 1:1    | 1:3    | 1:7    | 1:15   | 1:31   |
|---|--------|--------|--------|--------|--------|
| $q_{\varepsilon,h} = \frac{\varepsilon}{\mu_{h,*}}$ | 0.0462 | 00740  | 0.129  | 0.238  | 0.476  |
| $\delta u^{(0)}$                                    | 2.0e-2 | 7.0e-3 | 5.0e-3 | 4.8e-3 | 9.6e-3 |
| $\delta p^{(0)}$                                    | 1.0e-2 | 1.6e-2 | 1.3e-2 | 1.4e-2 | 3.5e-2 |
| $\delta p^{(1)}$                                    | 2.8e-4 | 2.1e-4 | 2.1e-4 | 7.1e-4 | 3.2e-3 |
| $\delta u^{(1)}$                                    | 4.9e-4 | 3.8e-4 | 4.2e-2 | 1.6e-3 | 1.1e-2 |
| $\delta u^{(2)}$                                    | 8.1e-6 | 7.5e-6 | 1.5e-5 | 1.2e-4 | 1.1e-3 |
| $\delta p^{(2)}$                                    | 1.2e-5 | 1.2-e5 | 3.0e-5 | 3.0e-4 | 4.1e-3 |
| $\delta u^{(3)}$                                    | 2.2e-7 | 2.7e-7 | 1.3e-6 | 2.2e-5 | 4.4e-4 |
| $\delta p^{(3)}$                                    | 3.3e-7 | 4.3e-7 | 2.7e-6 | 5.8e-5 | 1.4e-3 |

Table:  $\varepsilon = 10^{-2}, h = \frac{1}{512}$

## Model problem 2: numerical results

| ratio   | 1:1     | 1:3     | 1:7     | 1:15   | 1:31   |
|---|---------|---------|---------|--------|--------|
| $q_{\varepsilon,h} = \frac{\varepsilon}{\mu_{h,*}}$ | 0.00462 | 0.00740 | 0.0129  | 0.0238 | 0.0476 |
| $\delta u^{(0)}$                                    | 1.0e-3  | 7.0e-4  | 5.1e-4  | 5.3e-4 | 1.2e-4 |
| $\delta p^{(0)}$                                    | 2.0e-3  | 1.6e-3  | 1.3e-3  | 1.5e-3 | 4.3e-4 |
| $\delta p^{(1)}$                                    | 2.9e-6  | 2.2e-6  | 2.3e-6  | 7.9e-6 | 4.4e-5 |
| $\delta u^{(1)}$                                    | 5.0e-6  | 3.9e-6  | 4.5e-6  | 1.9e-5 | 1.4e-4 |
| $\delta u^{(2)}$                                    | 8.3e-9  | 7.7e-9  | 1.6e-8  | 1.3e-7 | 1.7e-6 |
| $\delta p^{(2)}$                                    | 1.2e-8  | 1.2e-8  | 3.2e-8  | 3.5e-7 | 5.9e-6 |
| $\delta u^{(3)}$                                    | 2.3e-11 | 5.2e-11 | 1.4e-10 | 1.0e-8 | 1.0e-7 |
| $\delta p^{(3)}$                                    | 3.2e-11 | 7.3e-11 | 3.0e-10 | 2.1e-8 | 2.9e-7 |

Table:  $\varepsilon = 10^{-3}, h = \frac{1}{512}$

Thank you for your attention